## **SWING CLAMPS (Spiral-Acting)**

R⊕∺S IMAO



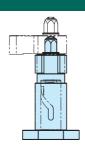
Body / Clamp-Arm Holder / Hex. Head	Clamp Arm		
SCM440 steel	S45C steel		
Quenched and tempered	Quenched and tempered		
Black oxide finish	Black oxide finish		

Counterclockwise Cl	
	66 55 N12×1.75
50 19 08	31(Clamp-Arm Travel)
08	105 Tol/Clamping Stroke)
\$\dphi 26\\\ \docorrow \text{Locating}\$	-

required in the robotized production line.

## Feature

The inside spiral groove allows the clamp arm to swing positively.



■With Clamp Arm

Part Number	Clamping Force (kN)	Allowable Screw Torque (N·m)	Clamping Direction	Weight (kg)		
PTSW2-12R	6	28	CW	0		
PTSW2-12L		20	CCW			

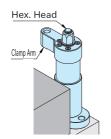
■Without Clamp Arm

Part Number	Clamping Force (kN)	Allowable Screw Torque (N·m)	Clamping Direction	Weight (kg)
PTSW2-12NR	6	00	CW	1.6
PTSW2-12NL	6	28	CCW	1.6

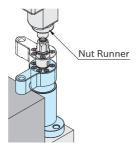
Note: If you prepare a custom clamp arm, contact us for the dimensional information on its mounting section. Note that custom clamp arms made by yourselves may cause clamping force to be increased or decreased.



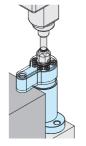
## How To Use



1. Unclamped Mode Load or unload a workpiece.



2. Ready-To-Clamp Mode When the hex. head is turned by a nut runner, the clamp arm swings fast to the clamping position.



3.Clamping Mode
The clamp arm moves down
for clamping. Using a nut
runner allows completing
positive clamping in a few
seconds.

## ✓ Note

A torque-settable impact wrench may also be used to operate these clamps.